

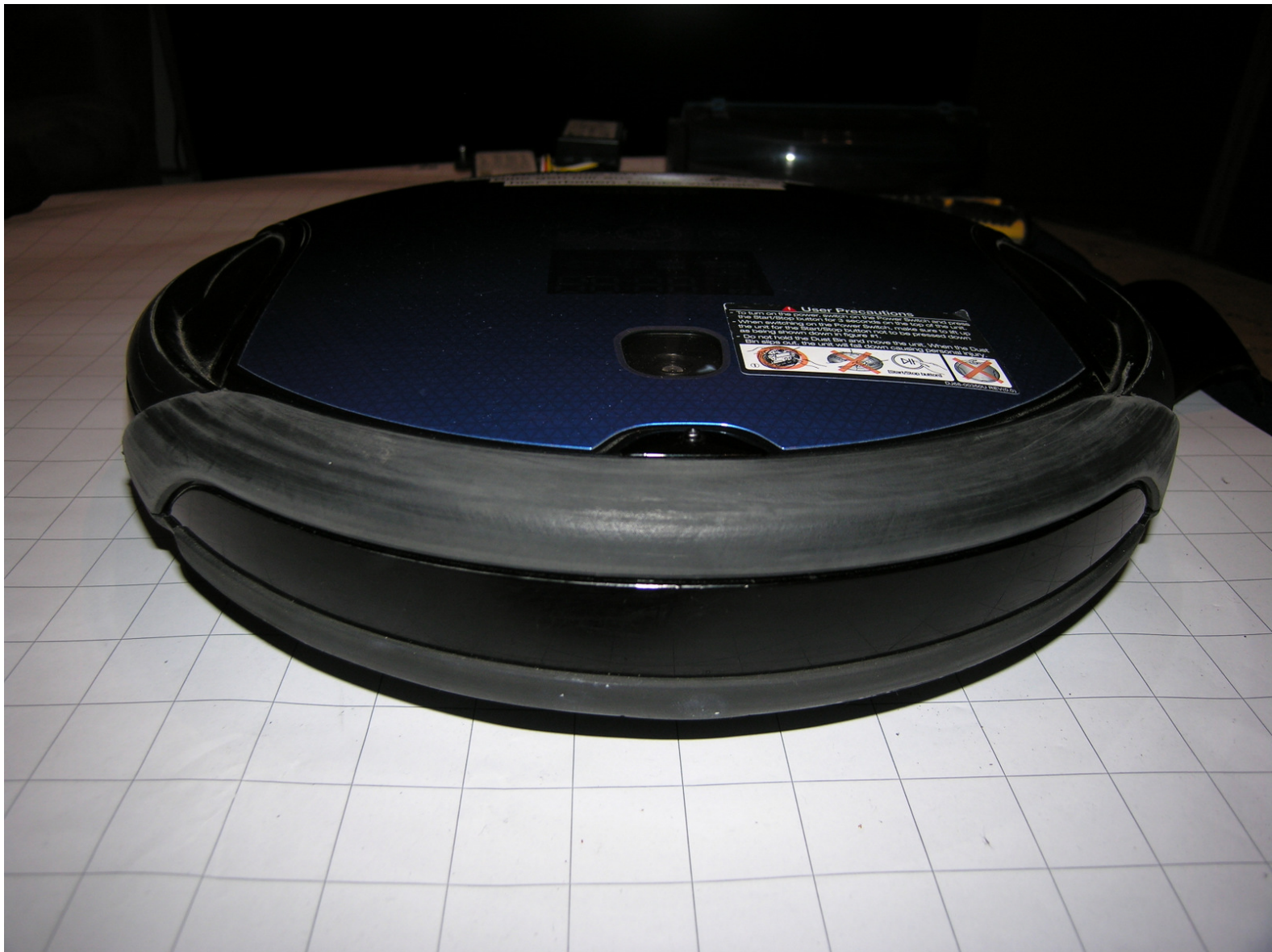


Samsung NaviBot SR8981 (VCR8981L3B-XEG)

Disassembly

An annotated guide to the Samsung NaviBot SR8981 (VCR8981L3B-XEG) to decompose into its individual parts.

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INTRODUCTION

An annotated guide to the Samsung NaviBot SR8981 (VCR8981L3B-XEG) to decompose into its individual parts.

The instructions in the comments of szantaiimre on the following page, has, helped me with slight adjustments (same manufacturer, different model, but similar enough)!

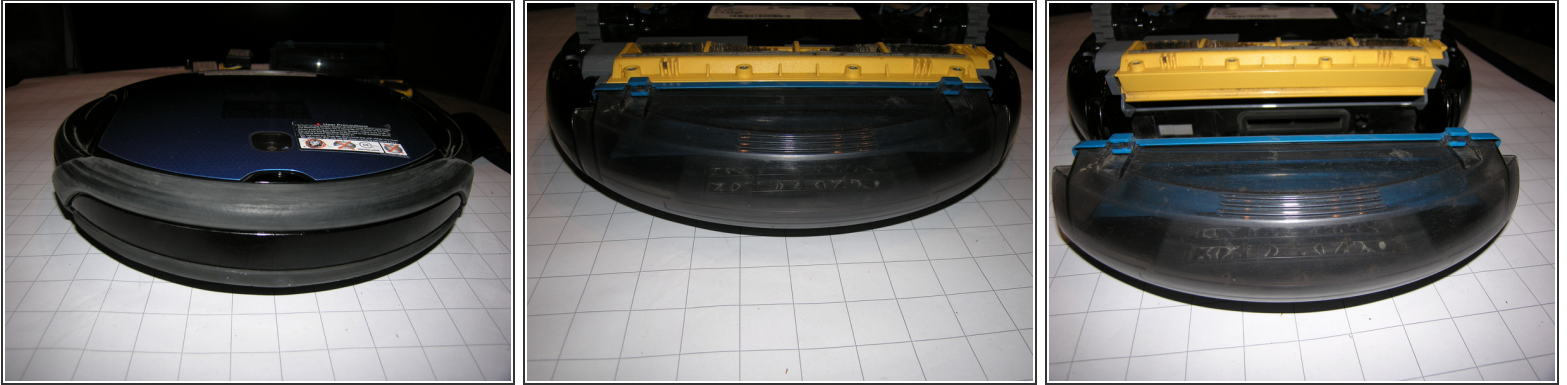
[How to disassemble Samsung NaviBot SR8875?](#)



TOOLS:

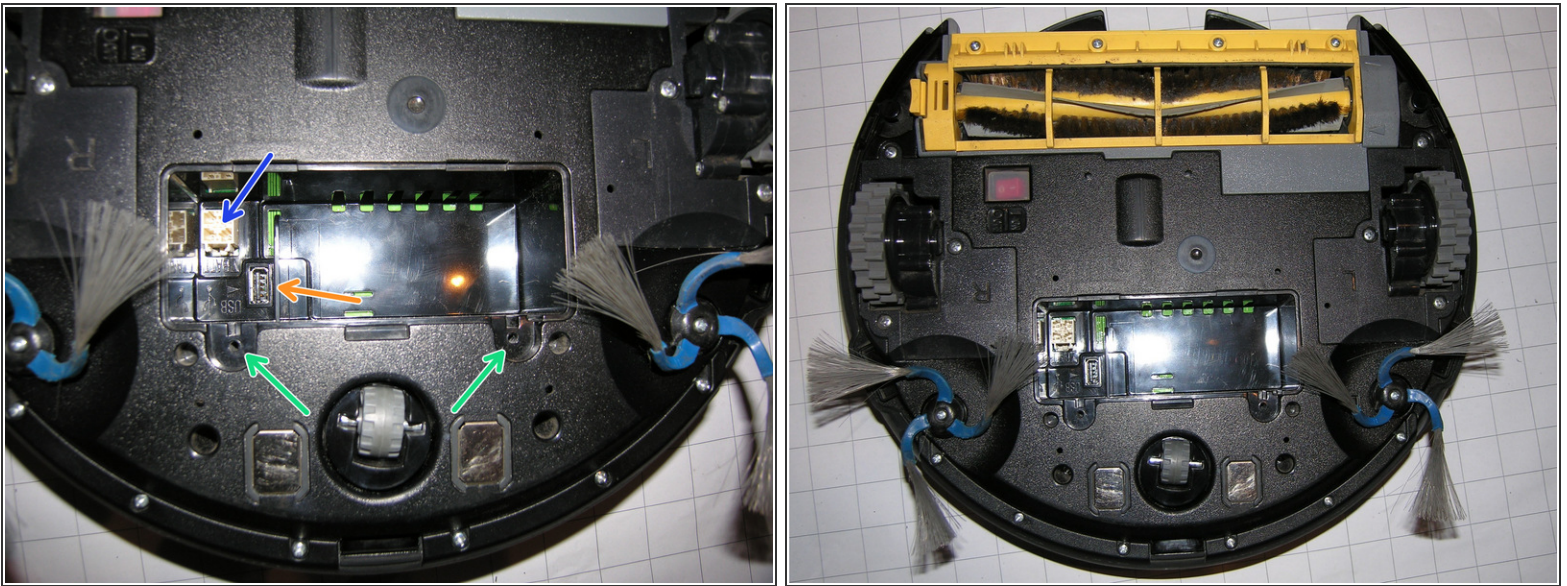
- [PH2 screwdriver](#) (1)
 - [Metal Spudger](#) (1)
 - [Spudger \(antistatischer Spatel\)](#) (1)
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Step 1 — Remove dust container



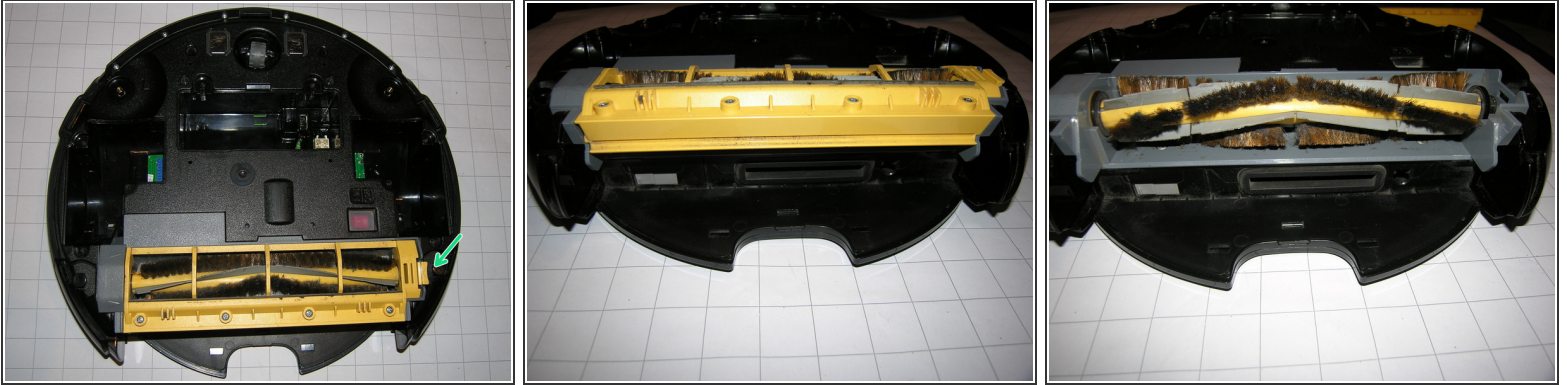
- First, remove the dust container from the SR8981.

Step 2 — Remove battery



- Screw the battery compartment at the points marked green and open the lid.
 - The blue arrow points to the connection between the battery and the casing. Once this is achieved, the battery can be taken out of the device.
- Note:** The orange arrow points to a USB interface, updates can be loaded probably modified the operating system through the or.

Step 3 — Removing the cover of the cleaning brush



- Open brush cover on the fastening clip (green arrow) and remove.

Step 4 — Dismantle cleaning brush



- The brush can be right slightly out the warehouse and then take out to right.

Step 5 — remove side panels



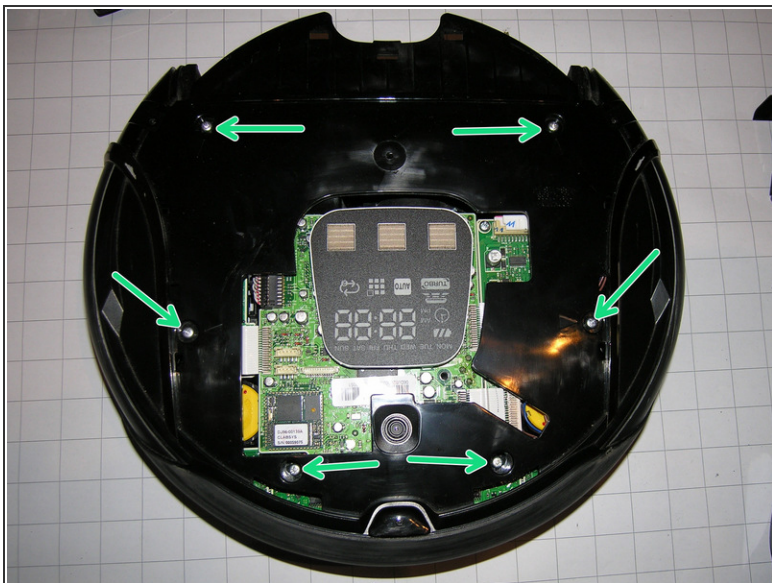
- The first picture shows the side view.
- Scene Two: The plastic strap (green arrow) of the side member must **carefully** over the plastic nose (blue arrow) are leveraged. Subsequently, the side panel can be pulled backwards.
- Third picture: The side panel has been pulled backwards, now the plastic strap (green arrow) and the plastic nose (blue arrow) are clearly visible.

Step 6 — Dismantle Top cover



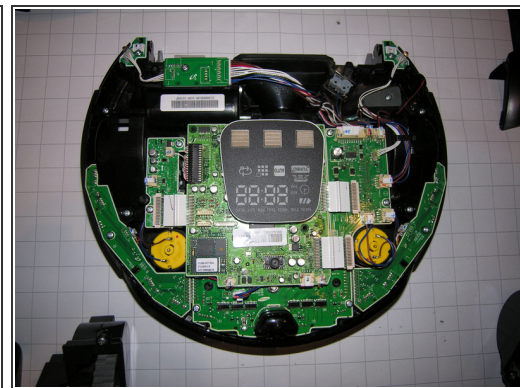
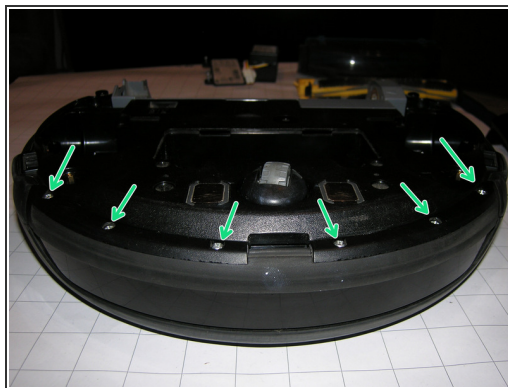
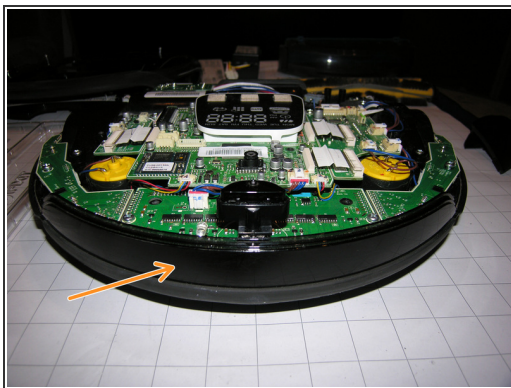
- Screws on the left (first picture) and solve the right
- Scene Two: Carefully remove the plastic claw and pry off the cover plate.
- Dritës image: the NaviBot without a cover plate

Step 7 — Remove intermediate level



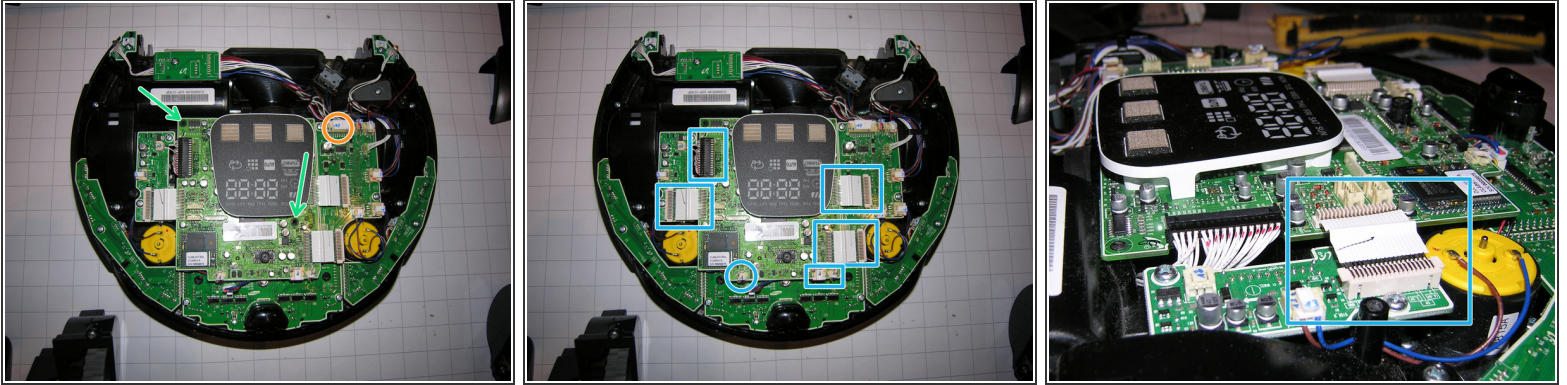
- Remove the marked screws (green arrows) and remove the intermediate level.

Step 8 — Front sensor cover



- To disassemble the front sensor cover, the six screws on the bottom (second picture) must be removed.

Step 9 — solve Motherboard

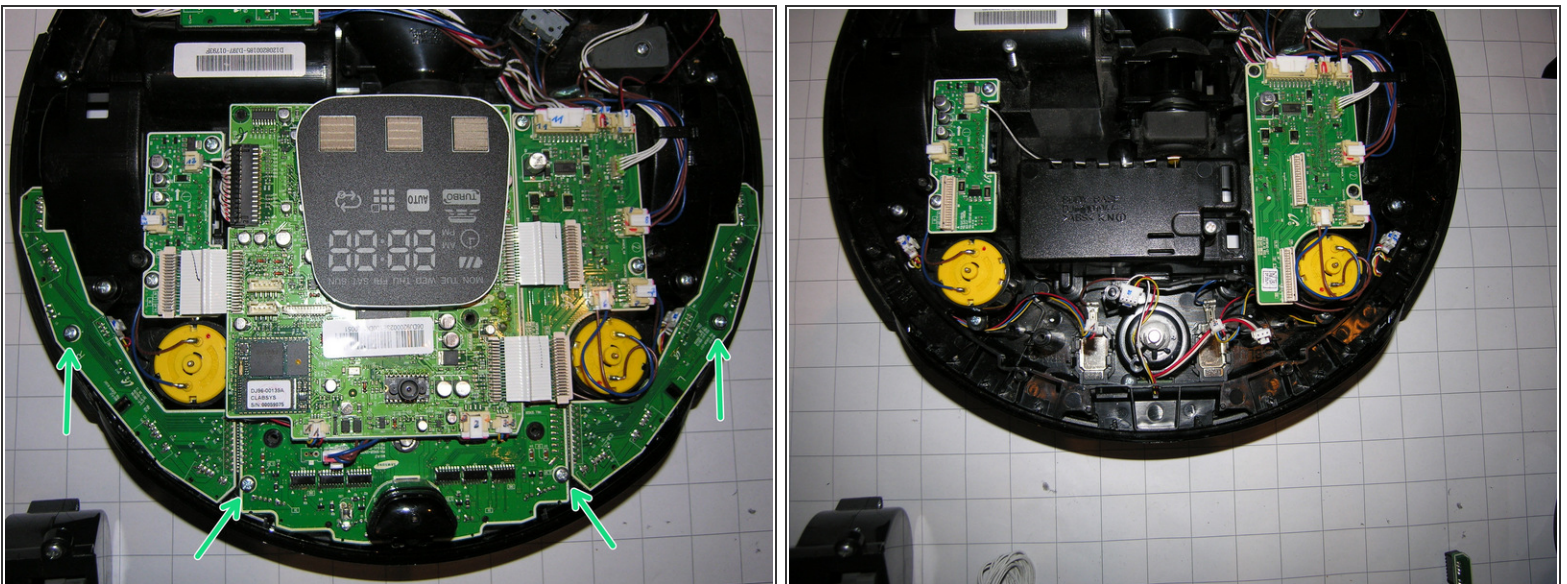


- Remove the screws on the green arrows.

i Note: As seen on the orange label, I have the plug-in connections, which do not explain themselves by their placement, both on the connector as well as the connector numbered. Thus, these are later easily assign again.

- Loosen the plug connections (Figure 2). **Caution:** specifically the rigid cable connections (Figure 3) are a bit difficult to open, and can be damaged without the entsprechende caution.

Step 10 — Dismantle sensor board



- Once the four front screws are loosened, the front divided into three parts, the sensor board can be removed.

Arbeite die Schritte in umgekehrter Reihenfolge ab, um dein Gerät wieder zusammenzubauen.

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